



RAMA UNIVERSITY

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FACULTY OF ENGINEERING

Digital Image Processing LECTURE-16

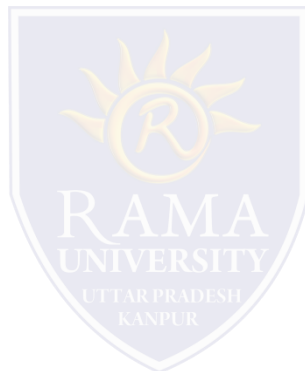
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OUTLINE

- ❖ **Spatial Filtering**
- ❖ **Neighborhood Averaging**
- ❖ **General Spatial Filter**
- ❖ **Non-linear Filter**
- ❖ **Sharpening Filters**
- ❖ **Derivatives**
- ❖ **MCQ**
- ❖ **References**



Spatial Filtering

Use of spatial masks for image processing (spatial filters)

Linear and nonlinear filters

Low-pass filters eliminate or attenuate high frequency components in the frequency domain

(sharp image details), and result in image blurring.

$$g(x,y) = \sum_{s=-a}^a \sum_{t=-b}^b w(s,t) f(x+s, y+t)$$

$a=(m-1)/2$ and $b=(n-1)/2$,

$m \times n$ (odd numbers)

For $x=0,1,\dots,M-1$ and $y=0,1,\dots,N-1$

The basic approach is to sum products between the mask coefficients and the intensities of the pixels under the mask at a specific location in the image:

$$R = w_1 z_1 + w_2 z_2 + \dots + w_9 z_9$$

Neighborhood Averaging

Each point in the smoothed image, $\hat{F}(x, y)$ is obtained from the average pixel value in a neighbourhood of (x, y) in the input image.

For example, if we use a 3×3 neighbourhood around each pixel we would use the mask

$$\begin{matrix} 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \end{matrix}$$



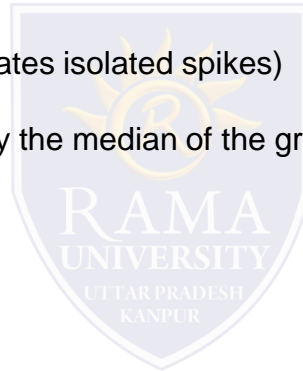
FIGURE 3.33

Another representation of a general 3×3 spatial filter mask.

w_1	w_2	w_3
w_4	w_5	w_6
w_7	w_8	w_9

Median filtering (nonlinear)

- Used primarily for noise reduction (eliminates isolated spikes)
- The gray level of each pixel is replaced by the median of the gray levels in the neighborhood of that pixel (instead of by the average as before).



Non-linear Filter

original



added noise



average



median



Sharpening Filters

- The main aim in image sharpening is to highlight fine detail in the image
- With image sharpening, we want to enhance the high-frequency components; this implies a spatial filter shape that has a high positive component at the centre

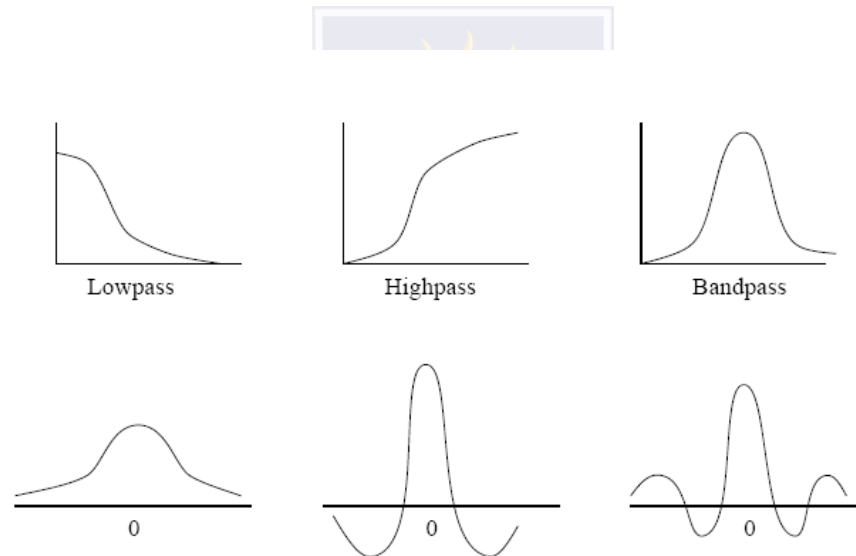


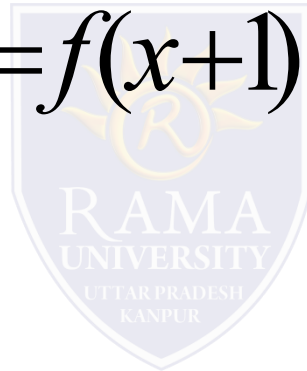
Figure 4: Frequency domain filters (top) and their corresponding spatial domain counterparts (bottom).

First derivative

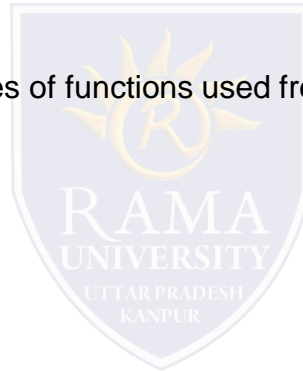
$$\frac{df}{dx} = f(x+1) - f(x)$$

Second derivative

$$\frac{d^2f}{dx^2} = f(x+1) + f(x-1) - 2f(x)$$



1. Which of the following expression is used to denote spatial domain process?
 - a) $g(x,y)=T[f(x,y)]$
 - b) $f(x+y)=T[g(x+y)]$
 - c) $g(xy)=T[f(xy)]$
 - d) $g(x-y)=T[f(x-y)]$
2. Which of the following shows three basic types of functions used frequently for image enhancement?
 - a) Linear, logarithmic and inverse law
 - b) Power law, logarithmic and inverse law
 - c) Linear, logarithmic and power law
 - d) Linear, exponential and inverse law
3. Which expression is obtained by performing the negative transformation on the negative of an image with gray levels in the range $[0,L-1]$?
 - a) $s=L+1-r$
 - b) $s=L+1+r$
 - c) $s=L-1-r$
 - d) $s=L-1+r$



4. What is the general form of representation of log transformation?

a) $s = c \log_{10}(1/r)$

b) $s = c \log_{10}(1+r)$

c) $s = c \log_{10}(1*r)$

d) $s = c \log_{10}(1-r)$

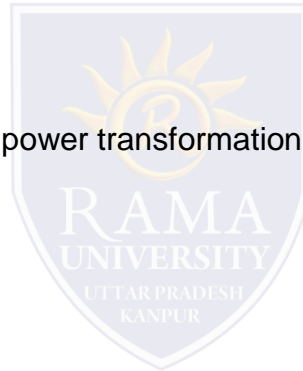
5. What is the general form of representation of power transformation?

a) $s = c r^y$

b) $c = s r^y$

c) $s = r c$

d) $s = r c^y$



References

- <https://www.javatpoint.com/digital-image-processing-tutorial>
- <https://www.geeksforgeeks.org/>
- Digital Image Processing 2nd Edition, Rafael C. Gonzalvez and Richard E. Woods. Published by: Pearson Education.
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- Fundamentals of Digital Image Processing, A.K. Jain. Published by Prentice Hall,Upper Saddle River, NJ.

