



RAMA UNIVERSITY

www.ramauniversity.ac.in

FACULTY OF ENGINEERING

Digital Image Processing LECTURE-35

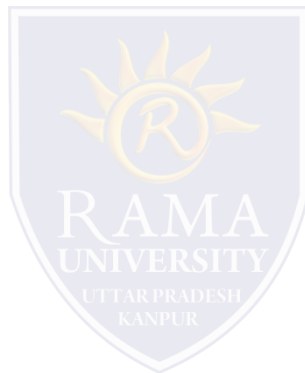
Mr. Dharendra

Assistant Professor

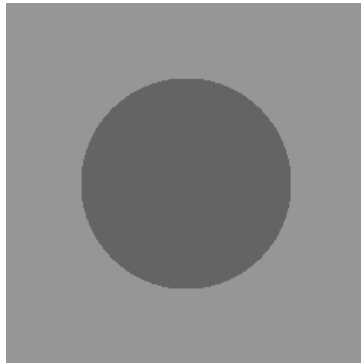
Computer Science & Engineering

OUTLINE

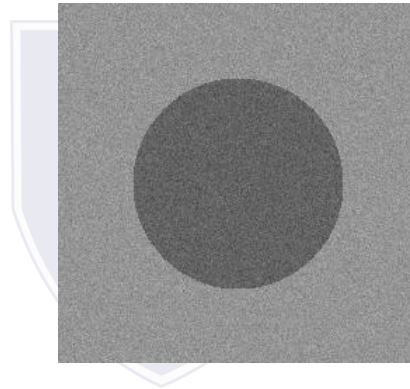
- ❖ **Greylevel histogram-based segmentation**
- ❖ **Greylevel thresholding**
- ❖ **MCQ**
- ❖ **References**



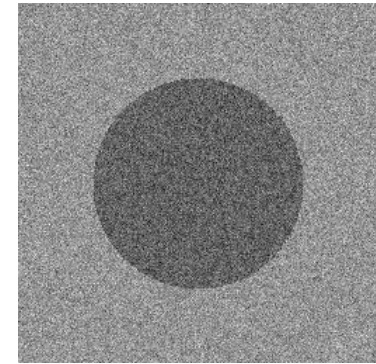
Greylevel histogram-based segmentation



Noise free



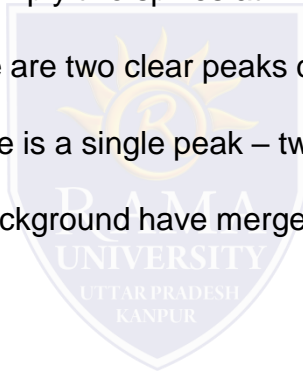
Low noise



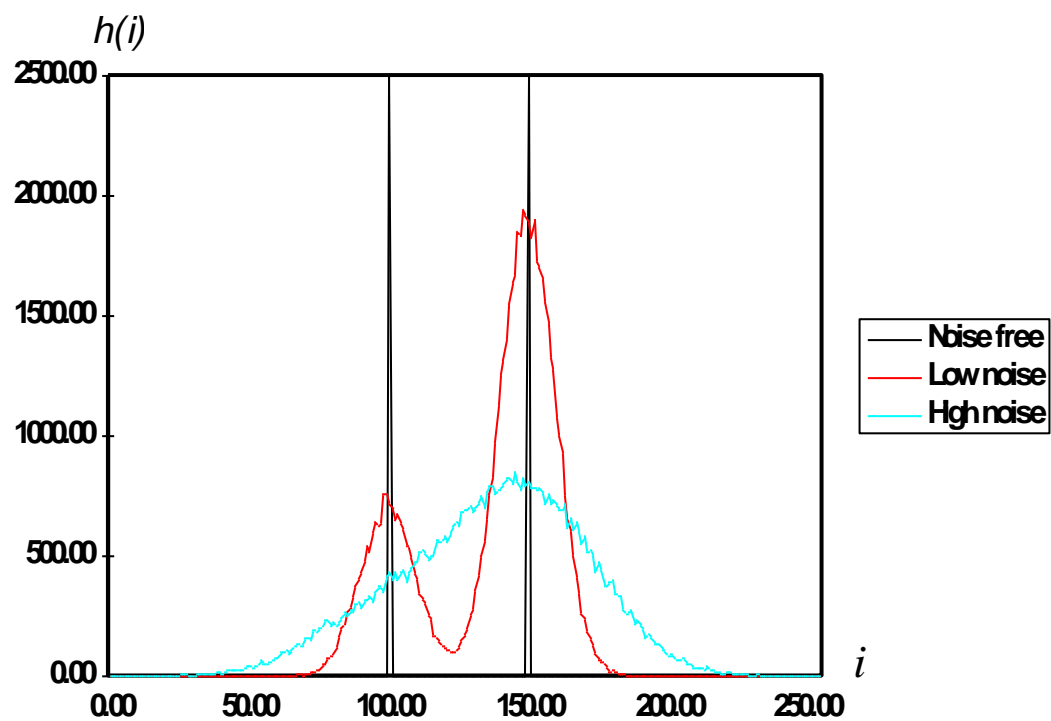
High noise

Greylevel histogram-based segmentation

- How do we characterise low noise and high noise?
- We can consider the histograms of our images
 - For the noise free image, its simply two spikes at $i=100$, $i=150$
 - For the low noise image, there are two clear peaks centred on $i=100$, $i=150$
 - For the high noise image, there is a single peak – two greylevel populations corresponding to object and background have merged

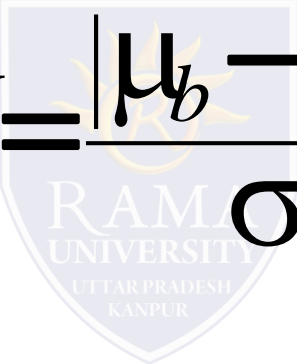


Greylevel histogram-based segmentation



Greylevel histogram-based segmentation

We can define the input image signal-to-noise ratio in terms of the mean greylevel value of the object pixels and background pixels and the additive noise standard deviation

$$S/N = \frac{|\mu_b - \mu_o|}{\sigma}$$
The watermark is a shield-shaped logo for Ram Lal University, Uttar Pradesh, Kanpur. It features a sunburst design at the top and the text 'RAM LAL UNIVERSITY' and 'UTTAR PRADESH KANPUR' below it.

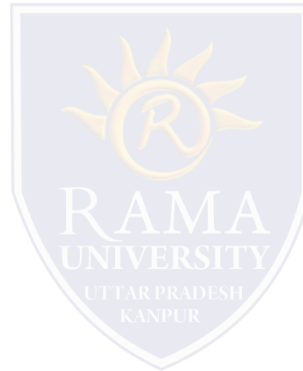
Greylevel histogram-based segmentation

For our test images :

S/N (noise free) = ∞

S/N (low noise) = 5

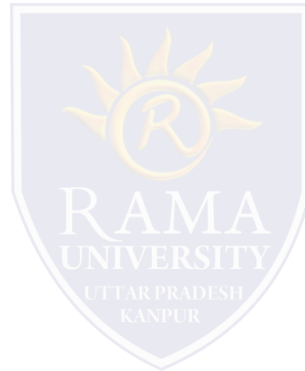
S/N (high noise) = 2



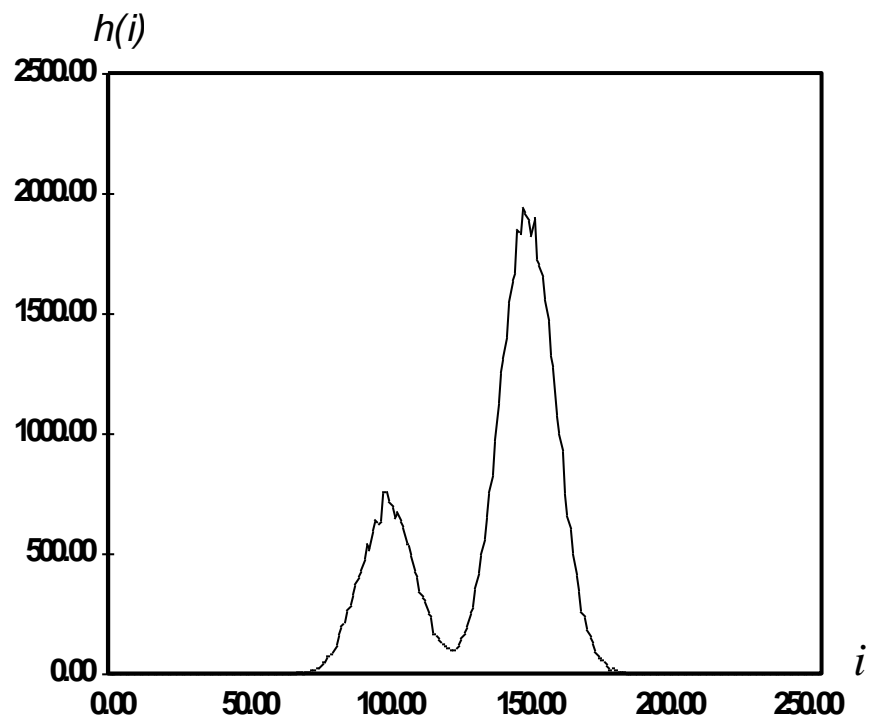
Greylevel thresholding

We can easily understand segmentation based on thresholding by looking at the histogram of the low noise object/background image

There is a clear 'valley' between to two peaks



Greylevel thresholding



1. The histogram of a digital image with gray levels in the range $[0, L-1]$ is represented by a discrete function:

- a) $h(r_k) = n_k$
- b) $h(r_k) = n/n_k$
- c) $p(r_k) = n_k$
- d) $h(r_k) = n_k/n$

2. How is the expression represented for the normalized histogram?

- a) $p(r_k) = n_k$
- b) $p(r_k) = n_k/n$
- c) $p(r_k) = nn_k$
- d) $p(r_k) = n/n_k$

3. Which of the following conditions does the $T(r)$ must satisfy?

- a) $T(r)$ is double-valued and monotonically decreasing in the interval $0 \leq r \leq 1$; and $0 \leq T(r) \leq 1$ for $0 \leq r \leq 1$
- b) $T(r)$ is double-valued and monotonically increasing in the interval $0 \leq r \leq 1$; and $0 \leq T(r) \leq 1$ for $0 \leq r \leq 1$
- c) $T(r)$ is single-valued and monotonically decreasing in the interval $0 \leq r \leq 1$; and $0 \leq T(r) \leq 1$ for $0 \leq r \leq 1$
- d) $T(r)$ is single-valued and monotonically increasing in the interval $0 \leq r \leq 1$; and $0 \leq T(r) \leq 1$ for $0 \leq r \leq 1$



4. The inverse transformation from s back to r is denoted as:

a) $s=T^{-1}(r)$ for $0 \leq s \leq 1$

b) $r=T^{-1}(s)$ for $0 \leq r \leq 1$

c) $r=T^{-1}(s)$ for $0 \leq s \leq 1$

d) $r=T^{-1}(s)$ for $0 \leq s \leq 1$

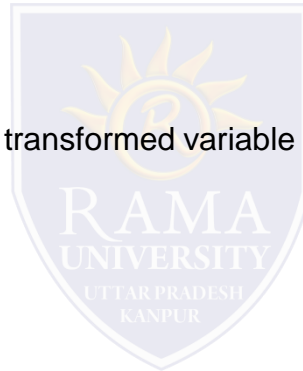
5. The probability density function $p_s(s)$ of the transformed variable s can be obtained by using which of the following formula?

a) $p_s(s) = p_r(r) |dr/ds|$

b) $p_s(s) = p_r(r) |ds/dr|$

c) $p_r(r) = p_s(s) |dr/ds|$

d) $p_s(s) = p_r(r) |dr/dr|$



References

- Dr. Mike Spann m.spann@bham.ac.uk <http://www.eee.bham.ac.uk/spannm>
- <https://www.javatpoint.com/digital-image-processing-tutorial>
- Henry Sambrooke Leigh, Carols of Cockayne, The Twins Morphological Image Processing (Digital Image Processing – Gonzalez/Woods)
- <https://www.geeksforgeeks.org/>
- Digital Image Processing 2nd Edition, Rafael C. Gonzalvez and Richard E. Woods. Published by: Pearson Education.
- Digital Image Processing and Computer Vision, R.J. Schalkoff. Published by: JohnWiley and Sons, NY.
- Fundamentals of Digital Image Processing, A.K. Jain. Published by Prentice Hall,Upper Saddle River, NJ.

