

FACULTY OF EGINEERING AND TECHNOLOGY

Soft Computing LECTURE -36

Umesh Kumar Gera
Assistant Professor
Computer Science & Engineering

OUTLINE

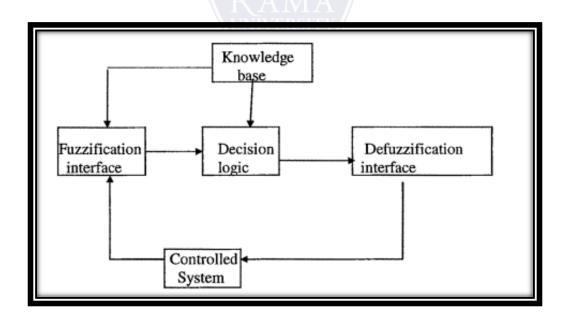
- Fuzzy Control
- Architecture of Fuzzy Control
- Mat lab
- Components of an Information Retrieval System
- Clustering of Document and Terms
- Steps of TSP using GA
- •Multiple Choice Question
- References

FUZZY CONTROL

Fuzzy Control

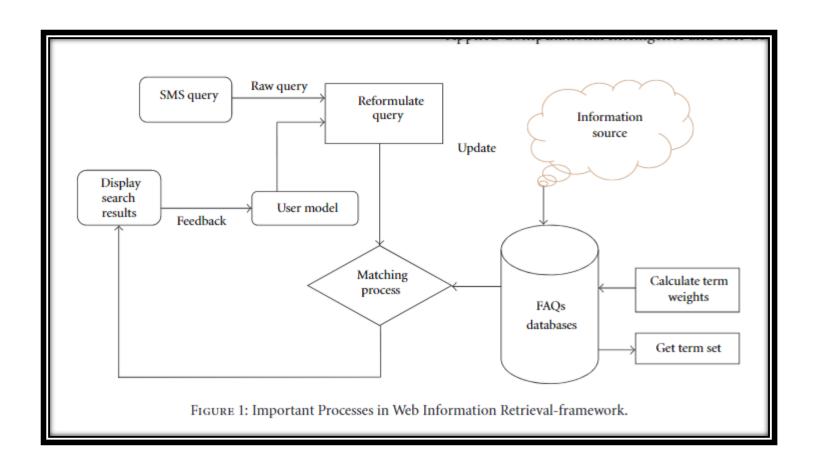
A control system is an arrangement of physical components designed to alter another physical system so that this system exhibits certain desired characteristics. Following are some reasons of using Fuzzy Logic in Control Systems –

- □While applying traditional control, one needs to know about the model and the objective function formulated in precise terms. This makes it very difficult to apply in many cases.
- □By applying fuzzy logic for control we can utilize the human expertise and experience for designing a controller.
- ☐ The fuzzy control rules, basically the IF-THEN rules, can be best utilized in designing a controller.



GENETIC ALGORITHM BASED INTERNET SEARCH TECHNIQUES

Important process in web information retrieval framework



Introduction to MATLAB Environment for Soft computing Techniques

The developments tools such as MATLAB, SIMULINK, and tools boxes are described in the section. Their use is illustrated by applications.

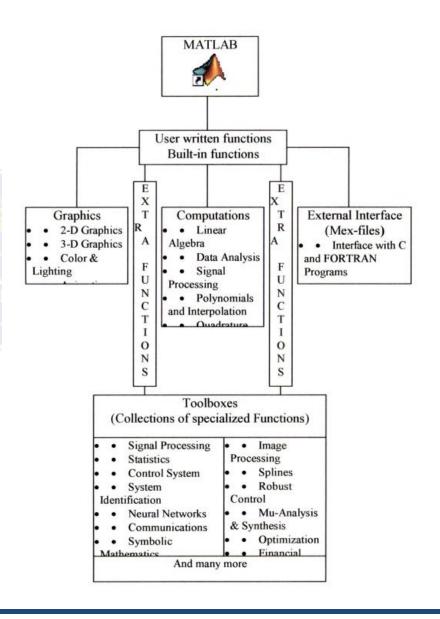
MATLAB [5] is a high-performance language for technical computing. The name MATLAB stands for matrix laboratory. A numerical analyst called Cleve Moler wrote the first version of MATLAB in the 1970s. It has since evolved into a successful commercial software package. The MATLAB system consists offive main parts:

MATLAB

The MATLAB Mathematical Function Library: -

This is a vast collection of computational algorithms ranging from elementary functions, like sum, sine, cosine, and complex arithmetic.

The MATLAB Language: - This is a high-level matrix/array language with control flow statements, functions, data structures, input/output, and object-oriented programming features.



MATLAB

The MATLAB Application Program Interface (API): -

This is a library that allows you to write C and Fortran programs that interact with MATLAB. It includes facilities for calling routines from MATLAB (dynamic linking), calling MATLAB as a computational engine, and for reading and writing MAT-files.

Toolboxes available in MATLAB 7.0 and used in the thesis are listed in table

| Control System Toolbox | Model Predictive Control Toolbox |
|------------------------|----------------------------------|
| Optimization Toolbox | Robust Control |
| Neural Network | Fuzzy Logic |
| TABLE 3.2: TO | OL BOXES used from MATLAB 7 |

MATLAB Function

There are various function some of them are listed in table.

| Functions | description |
|-----------|--------------------------------------|
| Addmf | Add a membership function to an FIS |
| Addrule | Add a rule to an FIS |
| Addyar | Add a variable to an FIS |
| Evalfis | Perform fuzzy inference calculations |
| Newfis | . Create new FIS |
| Trimf | Triangular membership function |
| | |

Neural Network Toolbox

There are various neural network toolbox listed below in table.

| Functions | description |
|-----------|--------------------------------------|
| Addmf | Add a membership function to an FIS |
| Addrule | Add a rule to an FIS |
| Addyar | Add a variable to an FIS |
| Evalfis | Perform fuzzy inference calculations |
| Newfis | . Create new FIS |
| Trimf | Triangular membership function |
| | |

Neural Network Toolbox

There are various neural network toolbox listed below in table.

The MATLAB neural network toolbox provides a complete set of functions and a graphical user interface for the design, implementation, and simulation of neural visualization. networks. It supports the most commonly used supervised and unsupervised network architectures and a comprehensive set of training and learning functions. The neural network toolbox extends the **MATLAB** computing environment to provide tools for the design, implementation, visualization, and simulation of neural network. Table 3.5 lists MATLAB functions used for training and learning of the ANN controller.

| Functions | description | |
|-------------------------------|---|--|
| newff: | Create a Feed forward back propagation network. | |
| purelin | Linear transfer function | |
| tansig | hyperbolic tangent sigmoid transfer function. | |
| Traingd | Gradient descent back propagation. | |
| sim | Simulation of simulink model | |
| gensim | Gnerate simulink block simulate a neural network. | |
| Train | trains a network NET according to | |
| | NET.trainFcn and NET.trainParam. | |
| Table 2.5. Employee AND Table | | |

Fuzzy Logic Algorithm

Initialization:

- · Define Linguistic variables and terms
- Construct Membership Functions
- Construct Rule Base

Fuzzification:

Convert crisp input data to fuzzy values using the membership functions

Inference:

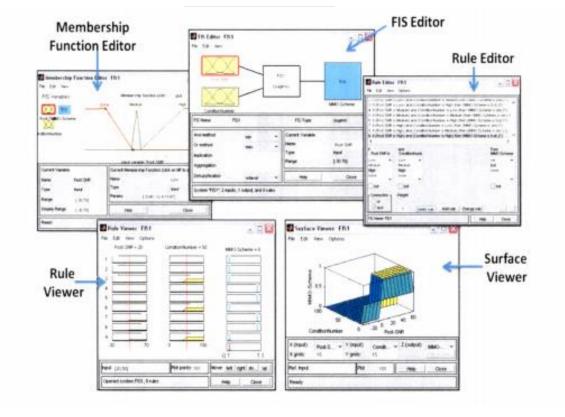
Evaluate the rules in the rule base and combine the results in rule base

Defuzzification:

Convert output data to non-fuzzy values

MATLAB Simulation-Fuzzy Logic Toolbox

MATLAB Simulation-Fuzzy Logic Toolbox The Fuzzy Logic Systems can be designed and simulated using MATLAB Fuzzy Logic Toolbox. The Fuzzy Logic Toolbox, provides functions and GUI based editors for building Fuzzy Inference System (FIS).



Fuzzy Inference System Editors and Viewers

List of FIS Editor Blocks and description

| FIS Editor Blocks | Description |
|-------------------------------|---|
| FIS Editor | Display general Information about FIS |
| Membership Function Editor | Display and edit the MFs associated with the input and output variables of FIS |
| Rule Base Editor | View and edit fuzzy rules |
| Rule Viewer | View detailed behavior of a FIS to help es diagnose the behavior of specific rul |
| Surface Viewer | Generates a 3-D surface from two input variables and the output of FIS |

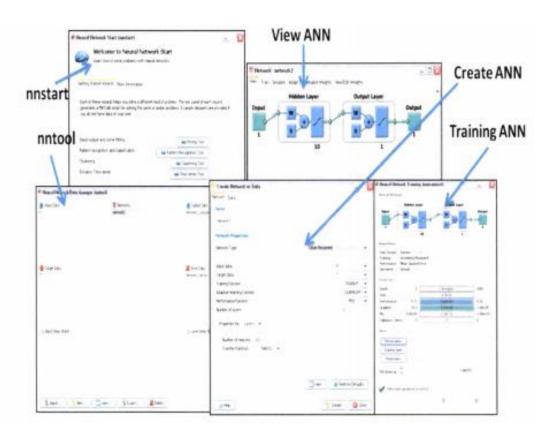
List of MATLAB Functions for Designing FIS

| MATLAB Function | Description |
|-----------------|--------------------------------------|
| newfis | Create new Fuzzy Inference System |
| readfis | Load FIS from File |
| evalfis | Perform Fuzzy Inference Calculations |
| addvar | Add variable to FIS |
| addmf | Add MF's tro FIS |
| addrule | Add rule to FIS |
| defuzz | Defuzzify Membershipo Functions |

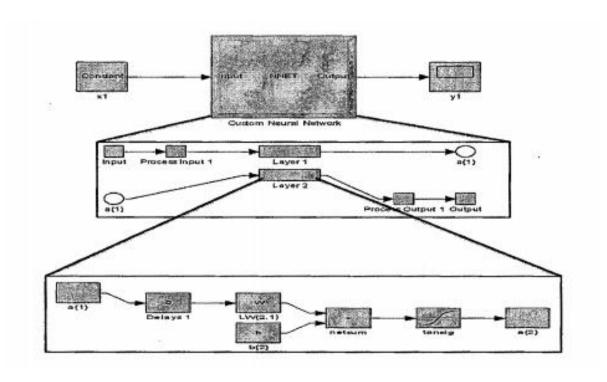
Designing Neural Network

- 1. Collection of data
- 2. Designing the network
- 3. Training the network
- 4. Testing the network

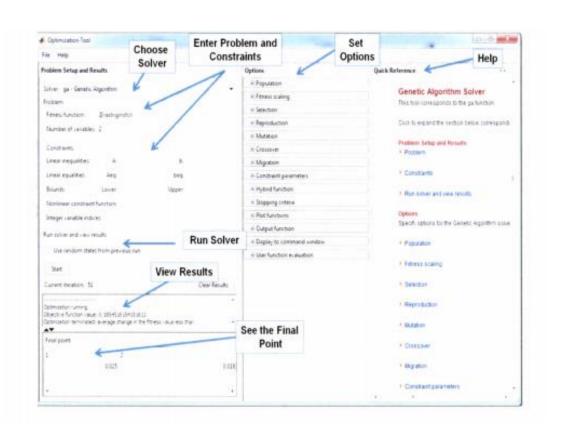
MATLAB Simulation: Neural Network Toolbox



Neural Network Simulink model



MATLAB Simulation: Global Optimization Toolbox



- 1. What is the output of the following code?
- A=[0 0 0; 0 9 0; 1 2 3]; nnz[A]
- a) 4
- b) 5
- c) 3
- d) Error
- 2. What is the output of the following code?
- A=[1 2 3; 32 23 26; 0 0 0]; spones(A)
- a) Returns a sparse matrix with the non-zeros replaced
- by normally distributed random numbers
- b) Returns a sparse matrix with the zeros replaced by
- ones
- c) Returns a sparse matrix with the non-zeros replaced
- by fractions
- d) Returns a sparse matrix with the non-zeros replaced
- by random numbers

- 3. The space located for the matrix generated from the spones command is
- a) Same as a sparse matrix
- b) Same as the original matrix
- c) Same as an identity matrix
- d) Double that of the sparse matrix
- 4. What is the output of the following code?
- A=[1 2 3; 4 5 6; 7 8 9];if(nzmax(A)==nzmax(spones(A)) disp('Yeah
- !')
- a) No output
- b) Error
- c) Yeah!
- d) Output suppressed
- 5. What is the output of the following code?
- nnz(spconvert([1 2 3; 4 5 6; 7 8 9])
- a) 3
- b) 2
- c) 1
- d) 6

- 6. What is the output of the following code? nzmax(spconvert([1 2 3; 4 5 6; 7 8 9])
- a) 2
- b) 3
- c) 1
- d) Error

View Answer

- 7. A memory for sparse matrix is dedicated by the _ command.
- a) spalloc
- b) sparsealloc
- c) allocspar
- d) no such command
- 8. What is the output of the following command? spalloc(2,3, 7)
- a) A 2*3 sparse matrix
- b) Memory is allocated for a 2*3 sparse matrix
- c) A 3*2 sparse matrix
- d) Error

- The default number of non-zero elements which can be put into the memory allocated by the spalloc command is > 1.
- a) True
- b) False
- 10. The pattern generated by the spy command is a measure of the number of zeros in the input matrix.
- a) True
- b) False

- 1. How can we smoothen the following graph of sin (t) and cos (t) into a circle?
- a) reduce the gap between linearly spaced elements of the dependent variable t
- b) reduce the gap between elements of the dependent variable t
- c) increase the gap between linearly spaced elements of the dependent variable t
- d) increase the gap between elements of the dependent variable t
- 2. Which command gives a title to the graph plotted by MATLAB?
- a) plot() generates the title itself
- b) title()
- c) hlabel()
- d) heading()
- 3. Which command enables a title for the x-axis?
- a) xlabel()
- b) horilabel()
- c) xlabel[]
- d) no command

- 4. Which command enables a title for the y-axis?
- a) vertlabel()
- b) ylabel()
- c) ylabel[]
- d) no command
- 5. How can several graphs for the same function be plotted on the same window?
- a) Contour plots
- b) Bode plots
- c) 3-D plots
- d) n-D plots

- 6. What is the output of the following command? meshgrid [x,y]
- a) two x*y matrices
- b) one x*y matrix
- c) one y*x matrix
- d) error
- 7. What is the output of the following code? t=0:0.001*pi:pi/2; plot(t,sin(t),*);
- a) An inverted sine curve
- b) A sine curve
- c) A point
- d) Error

- 8. What is the slope of the sawtooth waveform generated by the sawtooth command?
- a) 1/pi
- b) pi
- c) 1/(2*pi)
- d) 2*pi
- 9. What is the period of the sawtooth() waveform which is generated by the sawtooth() command?
- a) 2*pi
- b) pi*2
- c) pi
- d) 3*pi/2
- 10. The command used to generate an array of arrows
- is _____
- a) quiver[]
- b) arrows()
- c) quiver()
- d) arrows[]

| 11. What is the output of the following code? | 14. In the following code, what is the fundamental |
|---|--|
| =0:.001*pi:2*pi; plot(cos(t),sin(t)) | frequency of the sawtooth command? |
| a) A circle | f=1/50; sawtooth(2*pi*1/f*t) |
| o) A straight line | a) 50 |
| c) A unit circle | b) .02 |
| d) A sinusoid | c) 100 |
| | d) Error |
| 12. The period of sinusoidal curves can be changed in MATLAB. | |
| a) True | 15. The limits of the axes drawn are only specified in |
| p) False RAMA | the command used to plot the graph itself. |
| | a) True |
| 13. The command to draw the nature of a function over a default | b) False |
| fundamental period is | |
| a) ezplot() | |
| p) plot() | |
| c) stem() | |
| d) plot3() | |
| | |

- 1. Which command is suitable to change the axes of the graph plotted?
- a) axes
- b) axis
- c) yxaxes
- d) no command
- 2. What is the output of the following code? ezplot(x^2)
- a) No such command
- b) A parabola
- c) A part of a parabola
- d) Error
- 3. Which command can be used to generate multiple graphs in the same window?
- a) hold on
- b) wait
- c) not possible without contour command
- d) not possible

- 4. Inline functions can be plotted by the _____
 command.
- a) ezplot()
- b) plot3()
- c) plot()
- d) cannot be done
- 5. Which toolbox provides the plot command?
- a) Symbolic Maths Toolbox
- b) Signal Processing Toolbox
- c) Engineering Toolbox
- d) Functions

REFERENCES

- $\square_{\underline{https://www.javatpoint.com/artificial-neural-network-hopfield-network}$
- □https://www.geeksforgeeks.org/traveling-salesman-problem-using-genetic-algorithm/

