# Catalog

Microsoft PowerPoint - TOM-1 Notes.1 - Read-Only - Compatibility Mode.pdf	
TOM-1Notes.2.pdf ·····	
TOM-1Notes.3.pdf ·····	13
TOM-1Notes.4.pdf ·····	
TOM-1Notes.5.pdf ·····	
TOM-1Notes.6.pdf ·····	
TOM-1Notes.7.pdf ·····	
TOM-1Notes.8.pdf ·····	
TOM-1Notes.9.pdf ·····	
TOM-1Notes.10.pdf ·····	52
TOM-1Notes.11.pdf ·····	
TOM-1Notes.12.pdf ·····	
TOM-1Notes.13.pdf ·····	
TOM-1Notes.14.pdf ·····	76
TOM-1Notes.15.pdf ·······  TOM-1Notes.16.pdf ·······	82
TOM-1Notes.16.pdf ·····	88
TOM-1Notes.17.pdf	94
TOM-1Notes.18.pdf	99
TOM-1Notes.19.pdf ······	
TOM-1Notes.20.pdf ·····	
TOM-1Notes.21.pdf ·····	
TOM-1Notes.22.pdf ·····	
TOM-1Notes.23.pdf ·····	127
TOM-1Notes.24.pdf ·····	133
TOM-1Notes.25.pdf ·····	
TOM-1Notes.26.pdf ·····	
TOM-1Notes.27.pdf ·····	
TOM-1Notes.28.pdf ·····	154
TOM-1Notes.29.pdf ·····	161
TOM-1Notes.30.pdf ·····	166
TOM-1Notes.31.pdf ·····	171
TOM-1Notes.32.pdf ·····	176
TOM-1Notes.33.pdf ·····	182

	Remo
TOM-1Notes.34.pdf ······	
TOM-1Notes.35.pdf ······	
TOM-1Notes.36.pdf ······	198
TOM-1Notes.37.pdf ····································	
TOM-1Notes.38.pdf ····································	210
TOM-1Notes.39.pdf ····································	215
TOM-1Notes.40.pdf ····································	
TOM-1Notes.41.pdf ····································	227
TOM-1Notes.42.pdf ····································	233







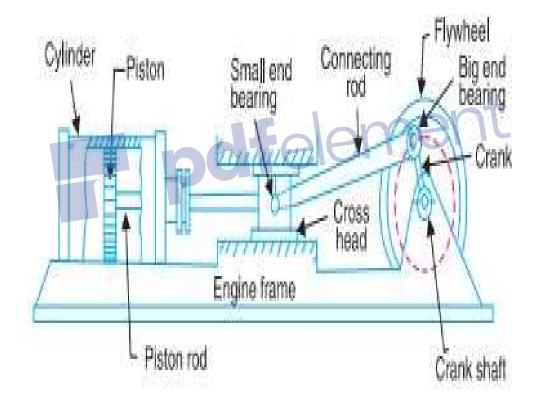
# FACULTY OF ENGINEERING & TECHNOLOGY

# **UNIT-I** Simple Mechanisms

## **Kinematic Link or Element**

Each part of a machine, which moves relative to some other part, is known as a kinematic link (or simply link) or element.

A link may consist of several parts, which are rigidly fastened together, so that they do not move relative to one another



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# Types of Links:

1. **Rigid link.** A rigid link is one which does not undergo any deformation while transmitting motion. Strictly speaking, rigid links do not exist. However, as the deformation of a connecting rod, crank etc. of a reciprocating steam engine is not appreciable, they can be considered as rigid links.

## 2. Flexible link.

A flexible link is one which is partly deformed in a manner not to affect the transmission of motion.

For example, belts, ropes, chains and wires are flexible links and transmit tensile forces only.

## 3. Fluid link.

A fluid link is one which is formed by having a fluid in a receptacle and the motion is transmitted through the fluid by pressure or compression only, as in the case of hydraulic presses, jacks and brakes.