



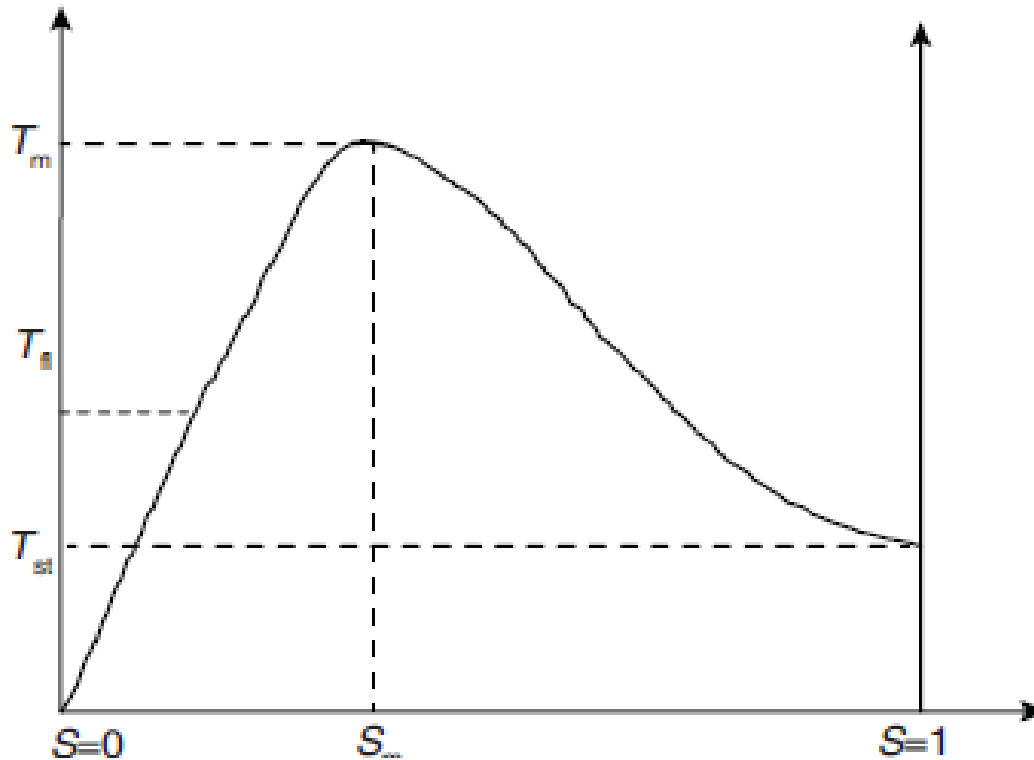
FACULTY OF ENGINEERING & TECHNOLOGY

Electrical Machine-ii

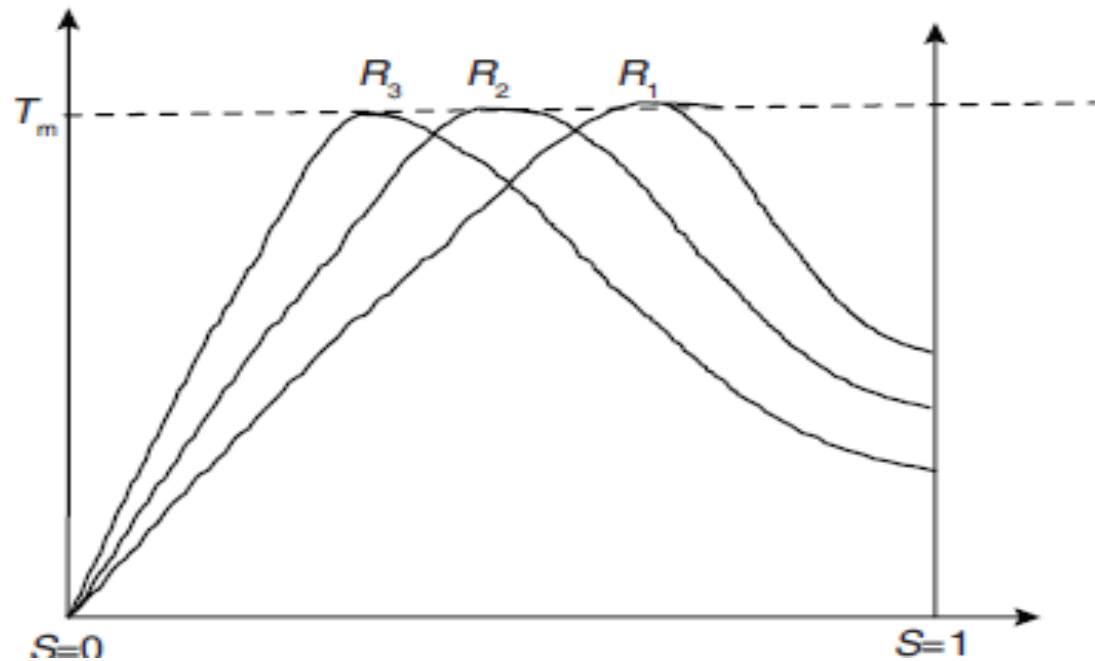
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TORQUE SLIP CHARACTERISTICS

- When slip $s = 0$, $N_r = N_s$. Under this condition, the motor stops. So the torque (T) at this value of s is zero. This shows that the torque slip characteristics starts from the origin.
- For smaller values of slip, the torque is directly proportional to the slip.
- For larger values of slip, the torque is inversely proportional to slip.



EFFECT OF ROTOR RESISTANCE ON TORQUE-SLIP CHARACTERISTIC



RATIO BETWEEN STARTING TORQUE AND MAXIMUM TORQUE

$$\frac{T_{st}}{T_{max}} = \frac{2s_m}{s_m^2 + 1}$$

Where T_{st} is the starting torque T_{max} is the maximum torque, s_m is the slip at maximum torque.

Requirement of Speed Control

- ❖ Speed control means change the drive speed as desired by the process to maintain different process parameter at different load .
- ❖ Energy Saving.
- ❖ Speed control is a different concept from speed regulation where there is natural change in speed due change in load on the shaft.
- ❖ Speed control is either done manually by the operator or by means of some automatic control device.
- ❖ Low speed starting requirement.



Methods of Speed Control of Induction motors

- ❖ Stator voltage Control
- ❖ Stator Frequency Control
- ❖ Stator Current Control
- ❖ V/F Control
- ❖ Static rotor resistance control